## Stochastic PDEs and their numerical approximation

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- Based on

Introduction to Computational Stochastic Partial Differential

## Equations

G. J. Lord, C. E. Powell, T. Shardlow CUP.


Informal description of SPDEs and numerical approximation.

(a) Deterministic vorticity
(b) Stochastic

Informal description of SPDEs and numerical approximation.

(a) Stochastic (Rough)
(b) Stochastic (Smooth)

Informal : will cut some corners !

## Some (other) reference books for SPDEs

- Semigroup approach to SPDEs
- Classic reference :

Da Prato, Giuseppe and Zabczyk, Jerzy
Stochastic Equations in Infinite Dimensions
Encyclopedia of Mathematics and its Applications
CUP, 1992. ISBN : 0-521-38529-6

- Chow, Pao-Liu

Stochastic Partial Differential Equations
Chapman \& Hall/CRC, Boca Raton, FL 2007, ISBN 978-1-58488-443-9; 1-58488-443-6

- Variational approach
- Prévôt, Claudia and Röckner, Michael

A concise course on stochastic partial differential equations Springer,2007, ISBN = 978-3-540-70780-6; 3-540-70780-8.

- Numerical methods
- Jentzen, Arnulf and Kloeden, Peter E.

Taylor approximations for stochastic partial differential equations
CBMS-NSF Regional Conference Series in Applied Mathematics SIAM, 2011, ISBN : 978-1-611972-00-9

- Physics approaches
- García-Ojalvo, Jordi and Sancho, José M.

Noise in spatially extended systems
Springer, ISBN 0-387-98855-6

- C. Gardiner

Stochastic Methods: A handbook for the natural and social sciences
Springer Series in Synergetics 2009, ISBN 978-3-540-70712-7

- SDEs : plenty of choice.
- Øksendal, Bernt,Stochastic Differential Equations,2003.

3-540-04758-1

## Background

- PDEs
- ODEs
- SDEs


## PDE

Many physical/biological models are described by parabolic PDEs

$$
\begin{equation*}
u_{t}=[\Delta u+f(u)] \quad u(0)=u^{0} \text { given } \quad u \in D \tag{1}
\end{equation*}
$$

+ BCs on $D$ bounded specified. $f(u)$ given where $u(t, \mathbf{x})$
Two typical examples:
- Nagumo equation

$$
u_{t}=\left[u_{x x}+u(1-u)(u-\alpha)\right] \quad u(x, t) \in \mathbb{R}, x \in[0, L], t>0
$$

- Allen-Cahn equation

$$
u_{t}=\left[u_{x x}+u-u^{3}\right] \quad u(x, t) \in \mathbb{R}, x \in[0,2 \pi), t>0
$$

- We write semilinear PDEs of form

$$
u_{t}=\Delta u+f(u)
$$

as ODE on Hilbert space $H\left(\operatorname{eg} L^{2}(D)\right)$.

$$
\frac{d u}{d t}=-A u+f(u)
$$

$A=-\Delta$

$$
u_{t}=-A u+f(u)
$$

Note - we could write solution in three ways :

- Integrate :

$$
u(t)=u(0)+\int_{0}^{t}(-A u+f(u)) d s
$$

Too restrictive on regularity of $u(t)$.
-Weak solution (multiply by test fn. Integ. by parts).

$$
\left\langle\frac{d u(s)}{d t}, v\right\rangle=-a(u(s), v)+\langle f(u(s)), v\rangle, \quad \forall v \in V
$$

where $a(u, v):=\left\langle A^{1 / 2} u, A^{1 / 2} v\right\rangle$

- Variation of constants

$$
u(t)=e^{-t A} u(0)+\int_{0}^{t} e^{-(t-s) A} f(u(s)) d s
$$

need to understand semigroup $e^{-t A}$ and its properties.

## PDE as infinite system of ODEs

$$
u_{t}=-A u+f(u), \quad u(0)=u^{0}
$$

- Look at weak solution

$$
\left\langle\frac{d u(s)}{d t}, v\right\rangle=-a(u(s), v)+\langle f(u(s)), v\rangle, \quad \forall v \in V
$$

- Write $u$ as a infinte series

$$
u(x, t)=\sum_{k \in \mathbb{Z}} u_{k} \phi_{k}(x)
$$

with $\phi_{k}$ e.func. and $\lambda_{k}$ e.val of $A$ (on $D+B C s$ )

- Subst. into PDE, take inner-product with $\phi_{k}$

$$
\frac{d u_{k}}{d t}=-\lambda_{k} u_{k}+f_{k}(u), \quad k \in \mathbb{Z}, \quad f(u)=\sum_{k} f_{k}(u) \phi_{k}
$$

Get infinite system of ODEs.
(truncation leads to spectral Galerkin approximation).

- Let's look at adding noise to ODE


## ODEs $\rightarrow$ SDEs \& Brownian Motion

In each Fourier mode have ODE of the form :Let's add noise

$$
\frac{d u}{d t}=\lambda u+f(u)+g(u) \frac{d \beta}{d t}
$$

with $\beta_{k}(t)$ Brownian motion.

$$
\beta=\left(\beta_{1}(t), \beta_{2}(t), \cdots, \beta_{n}(t)\right), \quad t \geq 0
$$

Is a (standard) Brownian motion or a Wiener process if for each $\beta_{j}$

- $\beta(0)=0$ a.s.
- Increments $\beta(t)-\beta(s)$ are normal $N(0, t-s)$, for $0 \leq s \leq t$. Equivalently $\beta(t)-\beta(s) \sim \sqrt{t-s} N(0,1)$.
- Increments $\beta(t)-\beta(s)$ and $\beta(\tau)-\beta(\sigma)$ are independent $0 \leq s \leq t \leq \sigma \leq \tau$.
Note: $\beta(t)=\beta(t)-0=\beta(t)-\beta(0) \sim N(0, t)$.
So $\mathbf{E}[\beta(t)]=0$ and variance $\operatorname{var}(\beta(t))=\mathbf{E}\left[\beta(t)^{2}\right]=t$.

Actually want a $W(t)$ on a filtered probability space and consider $\mathcal{F}_{t}$-Brownian motion.

- probability space $(\Omega, \mathcal{F}, P)$ consists of a sample space $\Omega$, a set of events $\mathcal{F}$ and a probability measure $P$.
- filtered probability space consists of $\left(\Omega, \mathcal{F}, \mathcal{F}_{t}, P\right)$ where $\mathcal{F}_{t}$ is a filtration of $\mathcal{F}$.
- The filtration $\mathcal{F}_{t}$ is a way of denoting the events that are observable by time $t$ and so as $t$ increases $\mathcal{F}_{t}$ contains more and more events.
- If $X(t), t \in[0, T]$ is $\mathcal{F}_{t}$ adapted then $X(t)$ is $\mathcal{F}_{t}$ measurable for all $t \in[0, T]$ (roughly $X(t)$ does not see into the future).
- Finally $X(t)$ is predictable if it is $\mathcal{F}_{t}$ adapted and can be approximated by a sequence $X\left(s_{j}\right) \rightarrow X(s)$ if $s_{j} \rightarrow s$ for all $s \in[0, T], s_{j}<s$.
- Letting $\beta_{n} \approx \beta\left(t_{n}\right), \Delta \beta_{n} \sim \sqrt{\Delta t} N(0,1)$

$$
\beta_{n+1}=\beta_{n}+\Delta \beta_{n}, \quad n=1,2, \ldots, N
$$

(a)

(b)

(c)

(a) Two discretised Brownian motions $W_{1}(t), W_{2}(t)$ constructed over $[0,5]$ with $N=5000$ so $\Delta t=0.001$.
(b) Brownian motion $W_{1}(t)$ plotted against $W_{2}(t)$. The paths start at $(0,0)$ and final point at $t=5$ is marked with a $\star$.
(c) Numerical derivatives of $W_{1}(t)$ and $W_{2}(t)$ from (a).

- Path $\beta(t)$ is continuous but not differentiable.

Since $\beta(t)$ is continuous but not differentiable. Understand

$$
\frac{d u}{d t}=\lambda u+f(u)+g(u) \frac{d \beta}{d t}
$$

as integral

$$
u(t)=u(0)+\int_{0}^{t}(\lambda u(s)+f(u(s))) d s+\int_{0}^{t} g(u) d \beta(s)
$$

Write as

$$
d u=[\lambda u+f(u)] d t+g(u) d W
$$

Ito stochastic integral $I(t)=\int_{0}^{t} g(u) d \beta(s)$

$$
I(t) \quad "=" \quad \lim _{N \rightarrow \infty} \sum_{n=1}^{N} g\left(t_{n-1}\right) \Delta \beta_{n} n
$$

The " $="$ is convergence in mean sqaure

$$
\mathbf{E}\left[\left\|X_{j}-X\right\|^{2}\right] \rightarrow 0, \quad \text { as } \quad j \rightarrow \infty
$$

- Look at Itô integrals only.

The Ito integral satisfies a number of nice properties.
$\rightarrow$ Martingale property that

$$
\mathbf{E}\left[\int_{0}^{t} g(s) d \beta(s)\right]=0
$$

- Ito isometry, given in one-dimension by

$$
\mathbf{E}\left[\left(\int_{0}^{t} g(s) d \beta(s)\right)^{2}\right]=\int_{0}^{t} \mathbf{E}\left[g(s)^{2}\right] d s
$$

- But Calculus is different. Chain rule :

Suppose $\frac{d u}{d t}=\lambda$. Let $\phi(u)=\frac{1}{2} u^{2}$. Then

$$
\frac{d \phi(u)}{d t}=\frac{d \phi}{d u} \frac{d u}{d t}=u \frac{d u}{d t}=\lambda u(t)
$$

- If $u(t)$ satisfies $d u=\lambda d t+\sigma d \beta(t)$.

The Itô formula says that for $\phi(u)=\frac{1}{2} u^{2}$.

$$
\begin{equation*}
d \phi(u)=u d u+\frac{\sigma^{2}}{2} d t \tag{2}
\end{equation*}
$$

and we pick up an unexpected extra term $\sigma^{2} / 2 d t$.

## Itô Formula

Itô SDE : $d u=[\lambda u+f(u)] d t+g(u) d \beta$
$\rightarrow$ Itô formula. $\phi(t, u)$ smooth

$$
d \Phi=\frac{\partial \Phi}{\partial t} d t+\frac{\partial \Phi}{\partial u} d u+\frac{1}{2} \frac{\partial^{2} \Phi}{\partial u^{2}} g^{2} d t
$$

or written in full

$$
\Phi(t, u(t))=\Phi\left(0, u_{0}\right)
$$

$$
+\int_{0}^{t} \frac{\partial \Phi}{\partial t}(s, u(s))+\frac{\partial \Phi}{\partial u}(s, u(s)) f(u(s))+\frac{1}{2} \frac{\partial^{2} \Phi}{\partial u^{2}}(s, u(s)) g(u(s))^{2} d s
$$

$$
+\int_{0}^{t} \frac{\partial \Phi}{\partial u}(s, u(s)) g(u(s)) d \beta(s)
$$

- Two standard applications: linear equations
- Ornstein Uhlenbeck (OU) process and
-Geometric Brownian Motion (GBM)


## Example: OU process

$$
d u=\lambda(\mu-u) d t+\sigma d \beta(t), \quad u(0)=u_{0}
$$

for $\lambda, \mu, \sigma \in \mathbb{R}$.
Itô formula with $\Phi(t, u)=e^{\lambda t} u$.

$$
d \Phi(t, u)=\lambda e^{\lambda t} u d t+e^{\lambda t} d u+0
$$

and using the SDE

$$
d \Phi(t, u)=\lambda e^{\lambda t} u d t+e^{\lambda t}(\lambda(\mu-u) d t+\sigma d \beta(t))
$$

As an integral equation
$\Phi(t, u(t))-\Phi\left(0, u_{0}\right)=e^{\lambda t} u(t)-u_{0}=\lambda \mu \int_{0}^{t} e^{\lambda s} d s+\sigma \int_{0}^{t} e^{\lambda s} d \beta(s)$.
After evaluating the deterministic integral, we find

$$
u(t)=e^{-\lambda t} u_{0}+\mu\left(1-e^{-\lambda t}\right)+\sigma \int_{0}^{t} e^{\lambda(s-t)} d \beta(s)
$$

and this is known as the variation of constants solution.
$u(t)=e^{-\lambda t} u_{0}+\mu\left(1-e^{-\lambda t}\right)+\sigma \int_{0}^{t} e^{\lambda(s-t)} d \beta(s)$
Using the mean zero property of the Itô integral

$$
\mu(t)=\mathbf{E}[u(t)]=e^{-\lambda t} u(0)+\mu\left(1-e^{-\lambda t}\right)
$$

so that $\mu(t) \rightarrow \mu$ as $t \rightarrow \infty$ and the process is "mean reverting". For the covariance, first note that

$$
\begin{aligned}
\operatorname{Cov} u(t), u(s) & =\mathbf{E}[(u(s)-\mathbf{E}[u(s)])(u(t)-\mathbf{E}[u(t)])] \\
& =\mathbf{E}\left[\int_{0}^{s} \sigma e^{\lambda(r-s)} d \beta(r) \int_{0}^{t} \sigma e^{\lambda(r-t)} d \beta(r)\right] \\
& =\sigma^{2} e^{-\lambda(s+t)} \mathbf{E}\left[\int_{0}^{s} e^{\lambda r} d \beta(r) \int_{0}^{t} e^{\lambda r} d \beta(r)\right] .
\end{aligned}
$$

Then, can show using the Itô isometry

$$
\operatorname{Cov} u(t), u(s)=\frac{\sigma^{2}}{2 \lambda} e^{-\lambda(s+t)}\left(e^{2 \lambda \min (s, t)}-1\right)
$$

In particular, the variance

$$
\operatorname{Var} u(t)=\sigma^{2}\left(1-e^{-2 \lambda t}\right) / 2 \lambda
$$

Then, $\operatorname{Var} u(t) \rightarrow \sigma^{2} / 2 \lambda$ and $u(t) \rightarrow N\left(\mu, \sigma^{2} / 2 \lambda\right)$ in distribution as $t \rightarrow \infty$.

## Example: OU process


(a)
(a) Two numerical solutions of the OU SDE and ODE $u(0)=1, \lambda=0.5$ and $\sigma=0.5$.
In (b) we examine the distribution at $t=100$ showing a histogram from 2000 different realisations.

- Will OU use later for stochastic heat equation.


## Example: Geometric Brownian Motion

$$
d u=r u d t+\sigma u d \beta(t)
$$

Solution :

$$
u(t)=\exp \left(\left(r-\sigma^{2} / 2\right) t+\sigma \beta(t)\right) u_{0}
$$

By the Itô formula with $\Phi(t, u)=\phi(u)=\log (u)$,

$$
d \phi(u)=r d t+\sigma d \beta(t)-\frac{1}{2} \sigma^{2} d t
$$

Hence,

$$
\phi(u(t))=\phi\left(u_{0}\right)+\int_{0}^{t}\left(r-\frac{\sigma^{2}}{2}\right) d s+\int_{0}^{t} \sigma d \beta(s)
$$

and $\log u(t)=\log \left(u_{0}\right)+\left(r-\frac{1}{2} \sigma^{2}\right) t+\sigma \beta(t)$.
Taking the exponential, get result.

## Systems of SDEs : $\mathbf{u} \in \mathbb{R}^{d}$.

- Given drift $\mathbf{f}(\mathbf{u}): \mathbb{R}^{d} \rightarrow \mathbb{R}^{d}$
- Diffusion $G(\mathbf{u}): \mathbb{R}^{d} \rightarrow \mathbb{R}^{d \times m}$
- $\boldsymbol{\beta}(t)=\left(\beta_{1}(t), \beta_{2}(2), \ldots, \beta_{m}(t)\right)^{T} \in \mathbb{R}^{m}$.

We write SDE as

$$
d \mathbf{u}=\mathbf{f}(\mathbf{u}) d t+G(\mathbf{u}) d \boldsymbol{\beta}(t)
$$

for integral

$$
\mathbf{u}(t)=\mathbf{u}(0)+\int_{0}^{t} \mathbf{f}(\mathbf{u}(s)) d s+\int_{0}^{t} G(\mathbf{u}(s)) d \boldsymbol{\beta}(s)
$$

## Approximate the Ito Stochastic DE:

SDE is an integral equation:

$$
u(t)=u(0)+\int_{0}^{t}[\lambda u+f(u(s))] d s+\int_{0}^{t} g(u(s)) d \beta(s) .
$$

- Let's get a numerical scheme : 1 step $t=\Delta t$

$$
\begin{aligned}
& u(t)=u(0)+\int_{0}^{t}(\lambda u+f(u(s))) d s+\int_{0}^{t} g(u(s)) d \beta(s) . \\
& u(\Delta t)=u(0)+\int_{0}^{\Delta t}[\lambda u(s)+f(u(s))] d s+\int_{0}^{\Delta t} g(u(s)) d \beta(s) . \\
& u(\Delta t) \approx u(0)+[\lambda u(0)+f(u(0))] \int_{0}^{\Delta t} d s+g(u(0)) \int_{0}^{\Delta t} d \beta(s) . \\
& u(\Delta t) \approx u(0)+\Delta t[\lambda u(0)+f(u(0))]+g(u(0)) \Delta \beta_{1} . \\
& u(\Delta t) \approx u(0)+\Delta t[\lambda u(0)+f(u(0))]+\sqrt{\Delta t} g(u(0)) \xi . \\
& \text { where } \xi \sim N(0,1) .
\end{aligned}
$$

Stability: GBM $d u=r u d t+\sigma u d \beta$
From solution of GBM see that $\mathbf{E}\left[u(t)^{2}\right]=e^{\left(2 r+\sigma^{2}\right) t} u_{0}^{2}$. Thus:

$$
\mathbf{E}\left[u(t)^{2}\right] \rightarrow 0 \text { provided } r+\sigma^{2} / 2<0 .
$$

EM method : $u_{n+1}=u_{n}+r u_{n} \Delta t+\sigma u_{n} \Delta \beta_{n}$.

$$
u_{n}=\prod_{j=0}^{n-1}\left(1+r \Delta t+\sigma \Delta \beta_{j}\right) u_{0}
$$

Second moment of $u_{n}$ is (using $\Delta \beta_{j}$ iid)

$$
\left.\mathbf{E}\left[u_{n}^{2}\right]=\prod_{j=0}^{n-1}\left((1+r \Delta t)^{2}+\sigma^{2} \Delta t\right)\right) u_{0}^{2}
$$

Thus $\mathbf{E}\left[u_{n}^{2}\right] \rightarrow 0$ as $n \rightarrow \infty$ if and only if

$$
\left|(1+r \Delta t)^{2}+\sigma^{2} \Delta t\right|=1+2 \Delta t\left(r+\sigma^{2} / 2+\Delta t r^{2} / 2\right)<1
$$

ie get a restriction on step size : $0<\Delta t<-2\left(r+\sigma^{2} / 2\right) / r^{2}$.

## Convergence: Strong \& Weak

- Strong convergence :
$\sup _{0 \leq t_{n} \leq T}\left\|\mathbf{u}\left(t_{n}\right)-\mathbf{u}_{n}\right\|_{L^{2}\left(\Omega, \mathbb{R}^{d}\right)}=\sup _{0 \leq t_{n} \leq T}\left(\mathbf{E}\left\|\mathbf{u}\left(t_{n}\right)-\mathbf{u}_{n}\right\|_{2}^{2}\right)^{1 / 2} \leq \Delta t^{p}$.
Care about approximating the sample path $\mathbf{u}(\cdot, \omega)$ Euler Maruyama
$O\left(\Delta t^{1 / 2}\right)$ multiplicative noise
$O\left(\Delta t^{1}\right)$ additive noise.
- Weak convergence: Estimate $\mathbf{E}[\phi(\mathbf{u}(T))]$

$$
\begin{gathered}
\mu_{M}:=\frac{1}{M} \sum_{j=1}^{M} \phi\left(\mathbf{u}_{N}^{j}\right) . \\
\mathbf{E}[\phi(\mathbf{u}(T))]-\mu_{M}=\underbrace{\left[\mathbf{E}[\phi(\mathbf{u}(T))]-\mathbf{E}\left[\phi\left(\mathbf{u}_{N}\right)\right]\right]}_{\text {weak discretization error }}+\underbrace{\left[\mathbf{E}\left[\phi\left(\mathbf{u}_{N}\right)\right]-\mu_{M}\right]}_{\text {Monte Carlo error }} .
\end{gathered}
$$

Care about the distributions. EM weak error $O(\Delta t)$.

## Recap

- PDE - $u_{t}=[\Delta u+f(u)]$
- Solutions: Weak solution \& Variations of Constants
- PDE as infinte system of ODEs
- SDEs : $d u=[\lambda u+f(u)] d t+g(u) d W$
- Brownian motion \& Ito integrals
- OU and GBM SDEs
- EM approximation

$$
v^{n+1}=v^{n}+\Delta t\left(\lambda v^{n}+f\left(v^{n}\right)\right)+\sqrt{\Delta t} g\left(v^{n}\right) \xi, \quad \xi \sim N(0,1) .
$$

- Stability : may need (semi-)implcit method.
- Convergence

$$
\operatorname{SPDE} u_{t}=[\Delta u+f(u)]+g(u) W_{t}
$$

- Introduce noise and covariance $Q$
- Introduce stochastic integral
- Solution
-Discretization


## Some example SPDEs

- What is an SPDE ?

PDEs with forcing that is random in both space and time.

- They include random fluctuations that occur in nature and are missing in deterministic PDE descriptions.
- Example:

Heat equation with a random term $\zeta(t, \mathbf{x})$

$$
u_{t}=\Delta u+\zeta(t, \mathbf{x}), \quad t>0, \quad \mathbf{x} \in D
$$

We will choose $\zeta=W_{t}$, where $W(t, \mathbf{x}, \omega)$ is a Wiener process.
Write SPDE as

$$
d u=\Delta u d t+d W, \quad t>0, \quad \mathbf{x} \in D
$$

## PDE + Additive Noise

Want to examine effects of noise $W(x, t)$

$$
d u=[\Delta u+f(u)] d t+g(u) d W
$$

- In time $d W$ is white (formally derivative of Brownian motion).
- In space either white or colored.
- Additive (or external) noise : $g(u)=\nu$ constant eg Allen-Cahn \& random external fluctuations:

$$
d u=\left[u_{x x}+u-u^{3}\right] d t+\nu d W
$$




## PDE + Multiplicative Noise

- Multiplicative (or intrinsic) noise $g(u)$ eg Nagumo \& noise on parmeter $\alpha$

$$
u_{t}=\left[u_{x x}+u(1-u)(u-\alpha)\right]
$$

$$
u_{t}=\left[u_{x x}+u(1-u)\left(u-\alpha+\sigma W_{t}\right)\right]
$$

$$
d u=\left[u_{x x}+u(1-u)(u-\alpha)\right] d t+\sigma u(u-1) d W
$$



## Vorticity

- model for large scale flows, e.g. related to climate modelling or the evolution of the red spot on Jupiter.
In two dimensions, the vorticity $u:=\nabla \times \mathbf{v}$ satisfies the PDE

$$
\begin{equation*}
u_{t}=\varepsilon \Delta u-(\mathbf{v} \cdot \nabla) u \tag{3}
\end{equation*}
$$

where $\Delta \psi=-u, \psi(t, \mathbf{x})$ is the scalar stream function, and $\mathbf{v}=\left(\psi_{y},-\psi_{x}\right)$.

- Additive noise captures small scale perturbations.

$$
\begin{equation*}
d u=[\varepsilon \Delta u-(\mathbf{v} \cdot \nabla) u] d t+\sigma d W(t) \tag{4}
\end{equation*}
$$




Deterministic
Stochastic

## filtering and sampling

- Suppose we have a signal $Y(x), x \geq 0$,

$$
\begin{equation*}
d Y=f(Y(x)) d x+\sqrt{\sigma} d \beta_{1}(x), \quad Y(0)=0 \tag{5}
\end{equation*}
$$

$f: \mathbb{R} \rightarrow \mathbb{R}$ is a given forcing term,
$\beta_{1}(x)$ is a Brownian motion,
$\sigma$ controls the strength of the noise.

- Noisy observations $Z(x)$ of the signal $Y(x)$.

$$
\begin{equation*}
d Z=Y(x) d x+\sqrt{\gamma} d \beta_{2}(x), \quad Z(0)=0 \tag{6}
\end{equation*}
$$

$\beta_{2}(x)$ is also a Brownian motion (independent of $\beta_{1}$ ) $\gamma$ determines the strength of the noise in the observation.
If $\gamma=0$, we observe the signal exactly.

- Goal :

Estimate the signal $Y(x)$ given observations $Z(x)$ for $x \in[0, b]$.

Can get estimate of signal from long time simulation of
$d u=\left[\frac{1}{\sigma}\left(u_{x x}-f(u) f^{\prime}(u)-\frac{\sigma}{2} f^{\prime \prime}(u)\right)\right] d t+\frac{1}{\gamma}\left[\frac{d Y}{d x}-u\right] d t+\sqrt{2} d W(t)$
for $(t, x) \in(0, \infty) \times[0, b]$ and where $W(t)$ is a space-time Wiener process.
Since $Y(x)$ is only Hölder continuous with exponent less than $1 / 2$, the derivative $\frac{d Y}{d x}$ and the SPDE (7) require careful interpretation.
(a)

(b)

(c)


- We now introduce for SPDEs
- the noise $W(t, \mathbf{x}, \omega)=W(t, \mathbf{x})=W(t)$
- stochastic Itô integral


## Wiener process

- Want to introduce space dependence into Brownian motion. Instead of working in $L^{2}(D)$ we develop theory on separable Hilbert space $U$ (so has orthonormal basis).
Denote norm $\|\cdot\|_{U}$ and inner product $\langle\cdot, \cdot\rangle_{U}$
- We start by defining $W(t, \mathbf{x})$ where $W$ has some spatial correlation.

We define the space $L^{2}(\Omega, H)$ :

$$
\|X\|_{L^{2}(\Omega, H)}^{2}=\mathbf{E}\left[\left(\|X\|_{H}\right)^{2}\right]<\infty
$$

## $Q$-Wiener process

- $Q$-Wiener process $\{W(t): t \geq 0\}$ is a $U$-valued process.

Each $W(t)$ is a $U$-valued Gaussian random variable and each has a well-defined covariance operator.
The covariance operator at $t=1$ is denoted $Q$.
Assumption
$Q \in \mathcal{L}(U)$ is

- non-negative $(\langle u, Q u\rangle \geq 0)$
- symmetric $(\langle u, Q u\rangle=\langle Q u, u\rangle)$
- $Q$ has orthonormal basis $\left\{\chi_{j}\right\}_{j \in \mathbb{N}}$ of eigenfunctions.

Corresponding eigenvalues $q_{j} \geq 0 . Q \chi_{j}=q_{j} \chi_{j}$.

- $Q$ is trace class i.e.

$$
\sum_{j=1}^{\infty} q_{j}<\infty
$$

Let $\left(\Omega, \mathcal{F}, \mathcal{F}_{t}, \mathbb{P}\right)$ be a filtered probability space.

- The filtration $\mathcal{F}_{t}$ is a way of denoting the events that are observable by time $t$ and so as $t$ increases $\mathcal{F}_{t}$ contains more and more events.
- If $X(t), t \in[0, T]$ is $\mathcal{F}_{t}$ adapted then $X(t)$ is $\mathcal{F}_{t}$ measurable for all $t \in[0, T]$ (roughly $X(t)$ does not see into the future).


## Definition ( $Q$-Wiener process)

Let $Q$ satisfy the Assumption. A $U$-valued stochastic process $\{W(t): t \geq 0\}$ is a $Q$-Wiener process if

1. $W(0)=0$ a.s.,
2. $W(t)$ is a continuous function $\mathbb{R}^{+} \rightarrow U$, for each $\omega \in \Omega$.
3. $W(t)$ is $\mathcal{F}_{t}$-adapted and $W(t)-W(s)$ is independent of $\mathcal{F}_{s}$, $s<t$,
4. $W(t)-W(s) \sim N(0,(t-s) Q)$ for all $0 \leq s \leq t$.

## Q-Wiener expansion

We now characterise a $Q$-Wiener process in a useful way.
Theorem
Let $Q$ satisfy the Assumption on noise.
Then $W(t)$ is a $Q$-Wiener process if and only if

$$
\begin{equation*}
W(t)=\sum_{j=1}^{\infty} \sqrt{q_{j}} \chi_{j} \beta_{j}(t), \tag{8}
\end{equation*}
$$

where $\beta_{j}(t)$ are iid $\mathcal{F}_{t}$-Brownian motions.
The series converges in $L^{2}(\Omega, U)$.
Proof : 1) Let $W(t)$ be a $Q$-Wiener process.
Since $\left\{\chi_{j}\right\}_{j \in \mathbb{N}}$ is an orthonormal basis for $U$,

$$
W(t)=\sum_{j=1}^{\infty}\left\langle W(t), \chi_{j}\right\rangle_{U} \chi_{j}
$$

Let $\beta_{j}(t):=\frac{1}{\sqrt{q_{j}}}\left\langle W(t), \chi_{j}\right\rangle_{U}$, so that (8) holds.

## Sketch of proof

2) Let's show $W(t)=\sum_{j=1}^{\infty} \sqrt{q_{j}} \chi_{j} \beta_{j}(t)$, converges in $L^{2}(\Omega, U)$. Consider the finite sum approximation

$$
\begin{equation*}
W^{J}(t):=\sum_{j=1}^{J} \sqrt{q_{j}} \chi_{j} \beta_{j}(t) \tag{9}
\end{equation*}
$$

- By orthonormality of eigenfunctions $\chi_{j} \&$ Parseval's identity

$$
\begin{equation*}
\left\|W^{J}(t)-W^{M}(t)\right\|_{U}^{2}=\sum_{j=M+1}^{J} q_{j} \beta_{j}(t)^{2} \tag{10}
\end{equation*}
$$

- Each $\beta_{j}(t)$ is a Brownian motion. Taking the expectation gives

$$
\mathbf{E}\left[\left\|W^{J}(t)-W^{M}(t)\right\|_{U}^{2}\right]=\sum_{j=M+1}^{J} q_{j} \mathbf{E}\left[\beta_{j}(t)^{2}\right]=t \sum_{j=M+1}^{J} q_{j} .
$$

As $Q$ is trace class, $\sum_{j=1}^{\infty} q_{j}<\infty$, and RHS $\rightarrow 0$ as $M, J \rightarrow \infty$.

## Example $W(t, x)$

$$
W(t)=\sum_{j=1}^{\infty} \sqrt{q_{j}} \chi_{j} \beta_{j}(t), \quad \text { a.s. }
$$

Let's take $U=L^{2}(D)$ for some domain $D$. Eg $D=(0,1)$.
We have

$$
W(t, x)=\sum_{j=1}^{\infty} \sqrt{q_{j}} \chi_{j}(x) \beta_{j}(t)
$$

We can specify eigenfunctions $\chi_{j}(x)$ and eigenvalues $q_{j}$ with appropriate decay rate.

- Let's construct $W(t) \in H_{0}^{r}(0,1)$.

Take $\chi_{j}(x)=\sqrt{2} \sin (j \pi x)$ and $q_{j}=|j|^{-(2 r+1+\epsilon)}$ for some $\epsilon>0$. So get

$$
W(t, x)=\sum|j|^{-(2 r+1+\epsilon) / 2} \sqrt{2} \sin (j \pi x) \beta_{j}(t)
$$

$$
W(t, x)=\sum|j|^{-(2 r+1+\epsilon) / 2} \sqrt{2} \sin (j \pi x) \beta_{j}(t)
$$

$W(t) \in H_{0}^{r}(0,1)$.
Check: For $r=0: W(t) \in L^{2}\left(\Omega, L^{2}(D)\right)$

$$
\|W\|_{L^{2}(D)}^{2}=\sum|j|^{-(1+\epsilon)} \beta_{j}(t)^{2}
$$

$$
\mathbf{E}\left[\|W\|_{L^{2}(D)}^{2}\right]=\sum t|j|^{-(1+\epsilon)}
$$

Check: For $r=1: W(t) \in L^{2}\left(\Omega, H_{0}^{1}(D)\right)$

$$
\begin{gathered}
W_{x}(t)=\sum|j|^{-(2+1+\epsilon) / 2} j \pi \sqrt{2} \cos (j \pi x) \beta_{j}(t) \\
\left\|W_{x}\right\|_{L^{2}(D)}^{2}=C \sum|j|^{-(2+1+\epsilon)} j^{2} \beta_{j}(t)^{2} \\
\mathbf{E}\left[\left\|W_{x}\right\|_{L^{2}(D)}^{2}\right]=C \sum t|j|^{-(1+\epsilon)}
\end{gathered}
$$

## Approximation of $W(t, x)$

Assume eigenfunctions $\chi_{j}$ and eigenvalues $q_{j}$ of $Q$ are known. Use finite sum to approximate $W(t)$ :

$$
W(t) \approx W^{J-1}(t):=\sum_{j=1}^{J-1} \sqrt{q_{j}} \chi_{j} \beta_{j}(t)
$$

Can compute increments of $W$ by

$$
W^{J-1}\left(t_{n+1}\right)-W^{J-1}\left(t_{n}\right)=\sqrt{\Delta t_{\text {ref }}} \sum_{j=1}^{J-1} \sqrt{q_{j}} \chi_{j} \zeta_{j}^{n}
$$

$\zeta_{j}^{n} \sim N(0,1)$.
To compute same sample path with larger time step $\Delta t=\kappa \Delta t_{\text {ref }}$

$$
W^{J}(t+\Delta t)-W^{J}(t)=\sum_{n=0}^{\kappa-1}\left(W^{J}\left(t+t_{n+1}\right)-W^{J}\left(t+t_{n}\right)\right)
$$

## Example $W(t) \in H_{0}^{r}(0, a)$

$$
W(t) \approx W^{J-1}(t):=\sum_{j=1}^{J-1} \sqrt{q_{j}} \sqrt{2} \sin (j \pi x) \beta_{j}(t)
$$

For effiecency use Discrete Sine Transform.
Sample $W(t, x)$ at $x_{k}=k a / J, k=1,2, \ldots, J-1$.
>> dtref=0.01; kappa=100; r=1/2; J=128; $\mathrm{a}=1$;
>> bj=get_onedD_bj(dtref,J,a,r);
>> dW=get_onedD_dW(bj,kappa,0,1);

```
function bj= get_onedD_bj(dtref, J,a,r)
jj = [1:J-1]'; myeps=0.001;
root_qj=jj.^-((2*r+1+myeps)/2);% set decay for H^r
bj=root_qj*sqrt(2*dtref/a);
```

Code to form the coefficients $b_{j}$.

- Inputs are dtref $=\Delta t_{\text {ref }}, \mathrm{J}=\mathrm{J}$, the domain size a, and regularity parameter $r=r$.
- Output is a vector bj of coefficients $b_{j}, j=1, \ldots, J-1$.

Here we fix $\epsilon=0.01$ in the definition of $q_{j}$ using myeps.

```
function dW=get_onedD_dW(bj,kappa,iFspace,M)
if(kappa==1)
    nn=randn(length(bj),M);
else
    nn=squeeze(sum(randn(length(bj),M,kappa),3));
end
X=bsxfun(@times,bj, nn);
if(iFspace==1)
    dW=X;
else
    dW=dst1(X);
end
```

Code to sample $W^{J-1}\left(t+\kappa \Delta t_{\text {ref }}, x_{k}\right)-W^{J-1}\left(t, x_{k}\right)$

- Inputs are : coefficients bj , kappa $=\kappa$, a flag iFspace, and the number $M$ of independent realisations to compute.
- If iFspace $=0$, the output $d W$ is a matrix of $M$ columns with $k$ th entry $W^{J}\left(t+\kappa \Delta t_{\text {ref }}, x_{k}\right)-W^{J}\left(t, x_{k}\right)$ for $k=1, \ldots, J-1$.
-If iFspace=1 then the columns of dW are the inverse DST of those for iFspace=0.
(b)



Approximate sample paths of the $Q$-Wiener process $W(t) \in H_{0}^{r}(0,1)$.
(a) $r=0$ and (b) $r=2$.

Generated with $J=128$ and $\Delta t_{\text {ref }}=0.01$.
In each case $W(t, 0)=W(t, 1)=0$.

## Q-Wiener process in two dimensions

Let $D=\left(0, a_{1}\right) \times\left(0, a_{2}\right)$ and $U=L^{2}(D)$.
Consider $Q \in \mathcal{L}(U)$ with eigenfunctions
$\chi_{j_{1}, j_{2}}(\mathbf{x})=\frac{1}{\sqrt{a_{1} a_{2}}} e^{2 \pi \mathrm{i}_{1} x_{1} / a_{1}} e^{2 \pi \mathrm{i} \mathrm{i}_{2} x_{2} / a_{2}}$ and, for a parameter $\alpha>0$ and $\lambda_{j_{1}, j_{2}}=j_{1}^{2}+j_{2}^{2}$, eigenvalues

$$
q_{j_{1}, j_{2}}=e^{-\alpha \lambda_{j_{1}, j_{2}}} .
$$

For even integers $J_{1}, J_{2}$, let

$$
W^{J}(t, \mathbf{x}):=\sum_{j_{1}=-J_{1} / 2+1}^{J_{1} / 2} \sum_{j_{2}=-J_{2} / 2+1}^{J_{2} / 2} \sqrt{q_{j_{1}, j_{2}}} \chi_{j_{1}, j_{2}}(\mathbf{x}) \beta_{j_{1}, j_{2}}(t),
$$

We generate two independent copies of $W^{J}\left(t, \mathbf{x}_{k_{1}, k_{2}}\right)$ using a single FFT.
>> J=[512,512]; dtref=0.01; kappa=100; a=[2*pi,2*pi];
>> alpha=0.05; bj = get_twod_bj(dtref,J,a,alpha);
>> [W1,W2]=get_twod_dW(bj,kappa,1);

```
function bj=get_twod_bj(dtref,J,a,alpha)
lambdax= 2*pi*[0:J(1)/2 -J(1)/2+1:-1]'/a(1);
lambday= 2*pi*[0:J(2)/2 -J (2)/2+1:-1]'/a(2);
[lambdaxx lambdayy]=meshgrid(lambday,lambdax);
root_qj=exp(-alpha*(lambdaxx.^2+lambdayy.^2)/2); % smooth
bj=root_qj*sqrt(dtref)*J(1)*J(2)/sqrt(a(1)*a(2));
```

```
function [dW1,dW2]=get_twod_dW(bj,kappa,M)
J=size(bj);
if(kappa==1)
    nnr=randn(J (1), J (2),M); nnc=randn(J (1), J (2), M);
else
    nnr=squeeze(sum(randn(J (1),J(2),M,kappa),4));
    nnc=squeeze(sum(randn(J (1),J(2),M,kappa),4));
end
nn2=nnr + sqrt(-1)*nnc; TMPHAT=bsxfun(@times,bj,nn2);
tmp=ifft2(TMPHAT); dW1=real(tmp); dW2=imag(tmp);
```


$\alpha=0.05$ and (b) $\alpha=0.5$
Computed with $J_{1}=J_{2}=512$ and at $t=1$.
Both processes take values in $H^{r}((0,2 \pi) \times(0,2 \pi))$ for any $r \geq 0$.

## Cylindrical Wiener process

When $Q=I, q_{j}=1$ for all $j$ then

$$
W(t)=\sum_{j=1}^{\infty} \chi_{j} \beta_{j}(t)
$$

This is white noise in space.

- Analogy with white light : homogeneous mix $\left(q_{j}=1\right)$ of all eigenfunctions.
- For a $Q$-Wiener process is coloured noise and the heterogeneity of the eigenvalues $q_{j}$ causes correlations in space.


## Problem:

However $Q$ is not trace class on $U$ so series does not converge.

- Trick:

Introduce $U_{1}$ such that $U \subset U_{1}$ and $Q=I$ is a trace class operator when extended to $U_{1}$.

## Definition (cylindrical Wiener process)

Let $U$ be a separable Hilbert space.
The cylindrical Wiener process (also called space-time white noise) is the process $W(t)$ defined by

$$
\begin{equation*}
W(t)=\sum_{j=1}^{\infty} \chi_{j} \beta_{j}(t) \tag{11}
\end{equation*}
$$

where $\left\{\chi_{j}\right\}_{j=1}^{\infty}$ is any orthonormal basis of $U$ and $\beta_{j}(t)$ are iid $\mathcal{F}_{t}$-Brownian motions.

If $U \subset U_{1}$ for a second Hilbert space $U_{1}$, the series converges in $L^{2}\left(\Omega, U_{1}\right)$ if the inclusion $\iota: U \rightarrow U_{1}$ is Hilbert-Schmidt.

## Itô integral

We now define for $W(t) Q$-Wiener process

$$
I(t)=\int_{0}^{t} B(s) d W(s)
$$

$W(t)$ takes values in the space $U$.
Will consider SPDEs in a Hilbert space $H$ so want $/$ to take values in $H$.
Thus want $B$ that are $\mathcal{L}\left(U_{0}, H\right)$-valued processes, for $U_{0} \subset U$.
Definition ( $L_{0}^{2}$ space for integrands)
Let $U_{0}=\left\{Q^{1 / 2} u: u \in U\right\}$ for $Q^{1 / 2}$.
$L_{0}^{2}$ is the set of linear operators $B: U_{0} \rightarrow H$ such that

$$
\|B\|_{L_{0}^{2}}:=\left(\sum_{j=1}^{\infty}\left\|B Q^{1 / 2} \chi_{j}\right\|^{2}\right)^{1 / 2}=\left\|B Q^{1 / 2}\right\|_{H S(U, H)}<\infty
$$

where $\chi_{j}$ is an orthonormal basis for $U$. $L_{0}^{2}$ is a Banach space with norm $\|\cdot\|_{L_{0}^{2}}$.

The truncated form $W^{J}(t)$ of the $Q$-Wiener process is finite-dimensional and the integral

$$
\begin{equation*}
\int_{0}^{t} B(s) d W^{J}(s)=\sum_{j=1}^{J} \int_{0}^{t} B(s) \sqrt{q_{j}} \chi_{j} d \beta_{j}(s) \tag{12}
\end{equation*}
$$

is well-defined.

- We can show the limit as $J \rightarrow \infty$ of (12) exists in $L^{2}(\Omega, H)$.

Define the stochastic integral by

$$
\begin{equation*}
\int_{0}^{t} B(s) d W(s):=\sum_{j=1}^{\infty} \int_{0}^{t} B(s) \sqrt{q_{j}} \chi_{j} d \beta_{j}(s) \tag{13}
\end{equation*}
$$

## Semilinear SPDEs

$$
d u=[-A u+f(u)] d t+G(u) d W(t), \quad u(0)=u_{0} \in H
$$

Global Lipschitz $f: H \rightarrow H, G: H \rightarrow L_{0}^{2}$.

## Assumption

Suppose $H$ is a Hilbert space with inner product $\langle\cdot, \cdot\rangle$ and $-A: \mathcal{D}(A) \subset H \rightarrow H$.
Suppose that $A$ has a complete orthonormal set of eigenfunctions $\left\{\phi_{j}: j \in \mathbb{N}\right\}$ and eigenvalues $\lambda_{j}>0$, ordered so that $\lambda_{j+1} \geq \lambda_{j}$.

Example: Stochastic Heat Equation with homogeneous Dirichlet BCs. Here $H=U=L^{2}(0, \pi)$,

$$
d u=\Delta u d t+\sigma d W(t), \quad u(0)=u_{0} \in L^{2}(0, \pi)
$$

$A=-\Delta$ with domain $\mathcal{D}(A)=H^{2}(0, \pi) \cap H_{0}^{1}(0, \pi)$.
Eigenvalues of $A$ are $\lambda_{j}=j^{2}$. $A$ satisfies the Assumption.
$A$ is the generator of an infinitesimal semigroup $S(t)=e^{-t A}$. $f=0$, and $G(u)=\sigma l$, so that $G(u) v=\sigma v$ for $v \in U$ and we have

## Solution: Strong

$$
d u=[-A u+f(u)] d t+G(u) d W(t)
$$

Definition (strong solution)
A predictable $H$-valued process $\{u(t): t \in[0, T]\}$ is called a strong solution if
$u(t)=u_{0}+\int_{0}^{t}[-A u(s)+f(u(s))] d s+\int_{0}^{t} G(u(s)) d W(s), \quad \forall t \in[0, T]$.

- Too restrictive in practice as need $u(t) \in \mathcal{D}(A)$.

Weak Solution: $d u=[-A u+f(u)] d t+G(u) d W(t)$

## Definition (weak solution)

A predictable $H$-valued process $\{u(t): t \in[0, T]\}$ is a weak solution if

$$
\begin{aligned}
\langle u(t), v\rangle= & \left\langle u_{0}, v\right\rangle+\int_{0}^{t}[-\langle u(s), A v\rangle+\langle f(u(s)), v\rangle] d s \\
& +\int_{0}^{t}\langle G(u(s)) d W(s), v\rangle, \quad \forall t \in[0, T], v \in \mathcal{D}(A),
\end{aligned}
$$

where

$$
\int_{0}^{t}\langle G(u(s)) d W(s), v\rangle:=\sum_{j=1}^{\infty} \int_{0}^{t}\left\langle G(u(s)) \sqrt{q_{j}} \chi_{j}, v\right\rangle d \beta_{j}(s) .
$$

- 'weak' refers to the PDE, not to the probabilistic notion of weak solution.
- (No condition on $d u / d t$, the test space is $\mathcal{D}(A)$, and $u(t) \in H)$


## stochastic heat equation (SHE) in one dimension

$$
\begin{array}{cc}
d u=\Delta u d t+\sigma d W(t), & u(0)=u_{0} \in L^{2}(0, \pi) \\
d u=-A u d t+\sigma d W(t), & u(0)=u_{0} \in L^{2}(0, \pi)
\end{array}
$$

$-A$ has e.funcs $\phi_{j}(x)=\sqrt{2 / \pi} \sin (j x)$ and e.vals $\lambda_{j}=j^{2}$ for $j \in \mathbb{N}$.

- Suppose for $W(t)$ the eigenfunctions $\chi_{j}$ of $Q$ are same as the eigenfunctions $\phi_{j}$ of $A$.
Weak solution satisfies, $v \in \mathcal{D}(A)$,

$$
\begin{aligned}
\langle u(t), v\rangle_{L^{2}(0, \pi)}= & \left\langle u_{0}, v\right\rangle_{L^{2}(0, \pi)}+\int_{0}^{t}\langle-u(s), A v\rangle_{L^{2}(0, \pi)} d s \\
& +\sum_{j=1}^{\infty} \int_{0}^{t} \sigma \sqrt{q_{j}}\left\langle\phi_{j}, v\right\rangle_{L^{2}(0, \pi)} d \beta_{j}(s) .
\end{aligned}
$$

Write $u(t)=\sum_{j=1}^{\infty} \hat{u}_{j}(t) \phi_{j}$ for $\hat{u}_{j}(t):=\left\langle u(t), \phi_{j}\right\rangle_{L^{2}(0, \pi)}$.
Take $v=\phi_{j}$, to get

$$
\hat{u}_{j}(t)=\hat{u}_{j}(0)+\int_{0}^{t}\left(-\lambda_{j}\right) \hat{u}_{j}(s) d s+\int_{0}^{t} \sigma \sqrt{q_{j}} d \beta_{j}(s) .
$$

$$
\hat{u}_{j}(t)=\hat{u}_{j}(0)+\int_{0}^{t}\left(-\lambda_{j}\right) \hat{u}_{j}(s) d s+\int_{0}^{t} \sigma \sqrt{q_{j}} d \beta_{j}(s), j \in \mathbb{N}
$$

- Hence, $\hat{u}_{j}(t)$ satisfies the SDE

$$
d \hat{u}_{j}=-\lambda_{j} \hat{u}_{j} d t+\sigma \sqrt{q_{j}} d \beta_{j}(t) .
$$

Each coefficient $\hat{u}_{j}(t)$ is an Ornstein-Uhlenbeck (OU) process which is a Gaussian process with variance

$$
\operatorname{Var}\left(\hat{u}_{j}(t)\right)=\frac{\sigma^{2} q_{j}}{2 \lambda_{j}}\left(1-e^{-2 \lambda_{j} t}\right)
$$

By the Parseval identity we obtain for $u_{0}=0$

$$
\|u(t)\|_{L^{2}\left(\Omega, L^{2}(0, \pi)\right)}^{2}=\mathbf{E}\left[\sum_{j=1}^{\infty}\left|\hat{u}_{j}(t)\right|^{2}\right]=\sum_{j=1}^{\infty} \frac{\sigma^{2} q_{j}}{2 \lambda_{j}}\left(1-e^{-2 \lambda_{j} t}\right) .
$$

$$
\|u(t)\|_{L^{2}\left(\Omega, L^{2}(0, \pi)\right)}^{2}=\mathbf{E}\left[\sum_{j=1}^{\infty}\left|\hat{u}_{j}(t)\right|^{2}\right]=\sum_{j=1}^{\infty} \frac{\sigma^{2} q_{j}}{2 \lambda_{j}}\left(1-e^{-2 \lambda_{j} t}\right) .
$$

- The series converges if the sum $\sum_{j=1}^{\infty} q_{j} / \lambda_{j}$ is finite.
- For a $Q$-Wiener process, the sum is finite because $Q$ is trace class. Hence solution $u(t)$ SHE is in $L^{2}(0, \pi)$ a.s.
- For a cylindrical Wiener process, $q_{j}=1$ and the sum is only finite if $\lambda_{j} \rightarrow \infty$ sufficiently quickly.
We have, $\lambda_{j}=j^{2}$ and $\sum_{j=1}^{\infty} \lambda_{j}^{-1}<\infty$. Thus, $\|u(t)\|_{L^{2}\left(\Omega, L^{2}(0, \pi)\right)}^{2}<\infty$. Hence solution $u(t) \in L^{2}(0, \pi)$ a.s.


## SHE in two dimensions

Repeat the calculations with $D=(0, \pi) \times(0, \pi)$.
$A$ has e.vals $\lambda_{j_{1}, j_{2}}=j_{1}^{2}+j_{2}^{2}$ and normalised e.funcs $\phi_{j_{1}, j_{2}}, j_{1}, j_{2} \in \mathbb{N}$.
Assume that $Q$ also has e.funcs $\phi_{j_{1}, j_{2}}$ and e.vals $q_{j_{1}, j_{2}}$.
Write $u(t)=\sum_{j_{1}, j_{2}=1}^{\infty} \hat{u}_{j_{1}, j_{2}}(t) \phi_{j_{1}, j_{2}}$.
Substituting $v=\phi_{j_{1}, j_{2}}$ into the weak form, each coefficient $\hat{u}_{j_{1}, j_{2}}(t)$ is an Ornstein-Uhlenbeck process:

$$
d \hat{u}_{j_{1}, j_{2}}=-\lambda_{j_{1}, j_{2}} \hat{u}_{j_{1}, j_{2}} d t+\sigma \sqrt{q_{j_{1}, j_{2}}} d \beta_{j_{1}, j_{2}}(t)
$$

and the variance

$$
\begin{gathered}
\operatorname{Var}\left(\hat{u}_{j_{1}, j_{2}}(t)\right)=\frac{\sigma^{2} q_{j_{1}, j_{2}}}{2 \lambda_{j_{1}, j_{2}}}\left(1-e^{-2 \lambda_{j_{1}, j_{2}} t}\right) . \\
\text { If } u_{0}=0, \mathbf{E}\left[\hat{u}_{j_{1}, j_{2}}(t)\right]=0 \text { and } \\
\|u(t)\|_{L^{2}\left(\Omega, L^{2}(D)\right)}^{2}=\mathbf{E}\left[\sum_{j_{1}, j_{2}=1}^{\infty}\left|\hat{u}_{j_{1}, j_{2}}(t)\right|^{2}\right]=\sum_{j_{1}, j_{2}=1}^{\infty} \frac{\sigma^{2} q_{j_{1}, j_{2}}}{2 \lambda_{j_{1}, j_{2}}}\left(1-e^{-2 \lambda_{j_{1}, j_{2}} t}\right) .
\end{gathered}
$$

$$
\|u(t)\|_{L^{2}\left(\Omega, L^{2}(D)\right)}^{2}=\sum_{j_{1}, j_{2}=1}^{\infty} \frac{\sigma^{2} q_{j_{1}, j_{2}}}{2 \lambda_{j_{1}, j_{2}}}\left(1-e^{-2 \lambda_{j_{1}, j_{2}} t}\right) .
$$

- When $Q$ is trace class, the right-hand side is finite. Solution $u(t) \in L^{2}(D)$ a.s.
- For a cylindrical Wiener process $\left(q_{j_{1}, j_{2}} \equiv 1\right)$, we have

$$
\sum_{j_{1}, j_{2}=1}^{\infty} \frac{1}{\lambda_{j_{1}, j_{2}}}=\sum_{j_{1}, j_{2}=1}^{\infty} \frac{1}{j_{1}^{2}+j_{2}^{2}}=\infty
$$

and the solution $u(t)$ is not in $L^{2}\left(\Omega, L^{2}(D)\right)$.
Do not expect weak solutions of SHE to exist in $L^{2}(D)$ in two dimensions.

- Need to take great care with cylindrical Wiener process !


## Mild solution of $d u=(-A u+f(u)) d t+G(u) d W$

A predictable $H$-valued process $\{u(t): t \in[0, T]\}$ is called a mild solution if for $t \in[0, T]$
$u(t)=e^{-t A} u_{0}+\int_{0}^{t} e^{-(t-s) A} f(u(s)) d s+\int_{0}^{t} e^{-(t-s) A} G(u(s)) d W(s)$,
where $e^{-t A}$ is the semigroup generated by $-A$.

- Expect that all strong solutions are weak solutions.
- Expect all weak solutions are mild solutions.
- Reverse implications hold for solutions with sufficient regularity.
- Existence and uniqueness theory of mild solutions is easiest to develop.

In addition to the global Lipschitz condition on $G$, the following condition is used.

## Assumption (Lipschitz condition on $G$ )

For constants $\zeta \in(0,2]$ and $L>0$, we have that $G: H \rightarrow L_{0}^{2}$ satisfies

$$
\begin{align*}
\left\|A^{(\zeta-1) / 2} G(u)\right\|_{L_{0}^{2}} & \leq L(1+\|u\|),  \tag{15}\\
\left\|A^{(\zeta-1) / 2}(G(u)-G(v))\right\|_{L_{0}^{2}} & \leq L\|u-v\|, \quad \forall u, v \in H .
\end{align*}
$$

For $\zeta>1$, the operator $A^{(\zeta-1) / 2}$ is unbounded
For $\zeta<1$, it is smoothing
(because $A^{(\zeta-1) / 2}: H \rightarrow \mathcal{D}\left(A^{\alpha}\right) \subset H$ for $\left.\alpha=(1-\zeta) / 2>0\right)$.
Think $\zeta=1$ - this is OK for $Q$ Wiener process.

## Existence and uniqueness

$$
d u=[-A u+f(u)] d t+G(u) d W(t), \quad u(0)=u_{0} \in H
$$

Suppose that $A$ satisfies Assumption on linear operator.
$f: H \rightarrow H$ satisfies the global Lipschitz condition
$G: H \rightarrow L_{0}^{2}$ satisfies Assumption on noise.
Suppose that the initial data $u_{0} \in L^{2}\left(\Omega, \mathcal{F}_{0}, L^{2}(D)\right)$.
Then, there exists a unique mild solution $u(t)$
$u(t)=e^{-t A} u_{0}+\int_{0}^{t} e^{-(t-s) A} f(u(s)) d s+\int_{0}^{t} e^{-(t-s) A} G(u(s)) d W(s)$,
Furthermore, there exists a constant $K_{T}>0$ such that

$$
\sup _{t \in[0, T]}\|u(t)\|_{L^{2}(\Omega, H)} \leq K_{T}\left(1+\left\|u_{0}\right\|_{L^{2}(\Omega, H)}\right)
$$

Proof: Standard fixed point argument.

## Regularity additive noise

$$
u(t)=e^{-t A} u_{0}+\int_{0}^{t} e^{-(t-s) A} f(u(s)) d s+\int_{0}^{t} e^{-(t-s) A} \sigma d W(s)
$$

Theorem (regularity in space for additive noise)
Let $G(u)=\sigma l$ and $\sigma \in \mathbb{R}$.
If $u_{0} \in L^{2}\left(\Omega, \mathcal{F}_{0}, \mathcal{D}(A)\right)$, then $u(t) \in L^{2}\left(\Omega, \mathcal{D}\left(A^{\zeta / 2}\right)\right)$ for $t \in[0, T]$. So

$$
\mathbf{E}\left[\|u(t)\|_{\zeta / 2}\right]:=\mathbf{E}\left[\left\|A^{\zeta / 2} u(t)\right\|\right]<\infty
$$

$\zeta=1: Q$-Wiener noise
Proof Split the mild solution into three terms, so that $u(t)=I+I I+$ III, for
$\mathrm{I}:=e^{-t A} u_{0}$, II $:=\int_{0}^{t} e^{-(t-s) A} f(u(s)) d s$, III $:=\int_{0}^{t} e^{-(t-s) A} \sigma d W(s)$.

- For the first term, since $u_{0} \in L^{2}\left(\Omega, \mathcal{F}_{0}, \mathcal{D}(A)\right)$,
$\mathbf{E}\left[\left\|e^{-t A} u_{0}\right\|_{\zeta / 2}^{2}\right] \leq \mathbf{E}\left[\left\|u_{0}\right\|_{1}^{2}\right]<\infty$ and $\mathrm{I} \in L^{2}\left(\Omega, \mathcal{D}\left(A^{\zeta / 2}\right)\right)$.
- The second term also belongs to $L^{2}\left(\Omega, \mathcal{D}\left(A^{\zeta / 2}\right)\right)$.

$$
\mathbf{E}\left[\|\operatorname{III}\|_{\zeta / 2}^{2}\right]=\mathbf{E}\left[\left\|\int_{0}^{t} e^{-(t-s) A} \sigma d W(s)\right\|_{\zeta / 2}^{2}\right]
$$

For term III, Itô's isometry gives

$$
\mathbf{E}\left[\|\operatorname{III}\|_{\zeta / 2}^{2}\right]=\sigma^{2} \int_{0}^{t}\left\|A^{\zeta / 2} e^{-(t-s) A}\right\|_{L_{0}^{2}}^{2} d s
$$

Now,

$$
\begin{aligned}
\int_{0}^{t}\left\|A^{\zeta / 2} e^{-(t-s) A}\right\|_{L_{0}^{2}}^{2} d s & =\int_{0}^{t}\left\|A^{(\zeta-1) / 2} A^{1 / 2} e^{-(t-s) A}\right\|_{L_{0}^{2}}^{2} d s \\
& \leq\left\|A^{(\zeta-1) / 2}\right\|_{L_{0}^{2}}^{2} \int_{0}^{t}\left\|A^{1 / 2} e^{-(t-s) A}\right\|_{\mathcal{L}(H)}^{2} d s
\end{aligned}
$$

The integral is finite by standard semigroup results. By Assumptions on $G\left\|A^{(\zeta-1) / 2}\right\|_{L_{0}^{2}}<\infty$.
Hence, III belongs to $L^{2}\left(\Omega, \mathcal{D}\left(A^{\zeta / 2}\right)\right)$.

## Reaction-diffusion equation, additive noise

Consider the SPDE

$$
d u=[A u+f(u)] d t+\sigma d W(t), \quad u(0)=u_{0} \in \mathcal{D}(A)
$$

with $A=-u_{x x}$ and $\mathcal{D}(A)=H^{2}(0, \pi) \cap H_{0}^{1}(0, \pi)$.
The operator $A$ has eigenvalues $\lambda_{j}=j^{2}$.

- For $Q$-Wiener process, can take $\zeta=1$ in Assumption 3 on $G$.

By our additive noise Theorem $7, u(t) \in L^{2}\left(\Omega, H^{1}(0, \pi)\right)$.
Our existence uniqueness only gave $L^{2}(0, \pi)$ spatial regularity.

- For space-time white noise (i.e., the cylindrical Wiener process), $\zeta \in(0,1 / 2)$, because

$$
\left\|A^{(\zeta-1) / 2} G(u)\right\|_{L_{0}^{2}}=\left(\operatorname{Tr} A^{(\zeta-1)}\right)^{1 / 2}
$$

and $\lambda_{j}^{(\zeta-1)}=\mathcal{O}\left(j^{2(\zeta-1)}\right)$.

- For the SHE in one dimension forced by space-time white noise takes values in $L^{2}\left(\Omega, H^{\zeta}(0, \pi)\right)$ and has up to a half (generalised) derivatives almost surely.


## Regularity in time

The exponents $\theta_{1}, \theta_{2}$ below determine rates of convergence for the numerical methods.
For simplicity assume $u_{0} \in \mathcal{D}(A)$.
$\operatorname{Eg} \zeta=1$ for Lipschitz $G$.
Lemma (regularity in time)
For $T>0, \epsilon \in(0, \zeta)$, and $\theta_{1}:=\min \{(\zeta-\epsilon) / 2,1 / 2\}$, there exists $K_{R T}>0$ such that

$$
\begin{equation*}
\left\|u\left(t_{2}\right)-u\left(t_{1}\right)\right\|_{L^{2}(\Omega, H)} \leq K_{R T}\left(t_{2}-t_{1}\right)^{\theta_{1}}, \quad 0 \leq t_{1} \leq t_{2} \leq T \tag{16}
\end{equation*}
$$

Further, for $\theta_{2}:=(\zeta-\epsilon) / 2$, there exits $K_{R T 2}>0$ such that

$$
\begin{equation*}
\left\|u\left(t_{2}\right)-u\left(t_{1}\right)-\int_{t_{1}}^{t_{2}} G(u(s)) d W(s)\right\|_{L^{2}(\Omega, H)} \leq K_{R T 2}\left(t_{2}-t_{1}\right)^{\theta_{2}} \tag{17}
\end{equation*}
$$

## Proof. (Start)

Write $u\left(t_{2}\right)-u\left(t_{1}\right)=$ I + II + III, where

$$
\begin{aligned}
\text { I: }= & \left(e^{-t_{2} A}-e^{-t_{1} A}\right) u_{0}, \text { II }:=\int_{0}^{t_{2}} e^{-\left(t_{2}-s\right) A} f(u(s)) d s-\int_{0}^{t_{1}} e^{-\left(t_{1}-s\right) A} f(u(s)) d s, \\
& \text { III }:=\left(\int_{0}^{t_{2}} e^{-\left(t_{2}-s\right) A} G(u(s)) d W(s)-\int_{0}^{t_{1}} e^{-\left(t_{1}-s\right) A} G(u(s)) d W(s)\right) .
\end{aligned}
$$

The estimation of I and II like in a deterministic case, except the $H$ norm replaced by the $L^{2}(\Omega, H)$ norm.
For III we write III $=I I I_{1}+I I I_{2}$, for

$$
\begin{aligned}
& \mathrm{III}_{1}:=\int_{0}^{t_{1}}\left(e^{-\left(t_{2}-s\right) A}-e^{-\left(t_{1}-s\right) A}\right) G(u(s)) d W(s) \\
& \mathrm{III}_{2}:=\int_{t_{1}}^{t_{2}} e^{-\left(t_{2}-s\right) A} G(u(s)) d W(s)
\end{aligned}
$$

Then use Itô isometry, assumption on $G$ and standard estimates from semigroup theory ...
... for three pages.

## Numerical methods

- We discretise in space : for example
- Finite differences
- Spectral Galerkin
- Galerkin Finite element
- Discretise in time : for example
- Euler-Maruyama
- Milstein
- Strong convergence

Look at

$$
\max _{0 \leq t_{n} \leq T}\left\|u\left(t_{n}\right)-\tilde{u}_{n}\right\|_{L^{2}(\Omega, H)}=\max _{0 \leq t_{n} \leq T} \mathbf{E}\left[\left\|u\left(t_{n}\right)-\tilde{u}_{n}\right\|_{H}\right]
$$

## Finite difference method

Examine reaction-diffusion equation with additive noise

$$
\begin{equation*}
d u=\left[\varepsilon u_{x x}+f(u)\right] d t+\sigma d W(t), \quad u(0, x)=u_{0}(x) \tag{18}
\end{equation*}
$$

homogeneous Dirichlet boundary conditions on $(0, a)$.
$W(t)$ a $Q$-Wiener process on $L^{2}(0, a)$.

- Introduce the grid points $x_{j}=j h$ for $h=a / J$ and $j=0, \ldots, J$. Use centred difference approximation $A^{\mathrm{D}} \approx \Delta$

$$
A^{\mathrm{D}}:=\frac{1}{h^{2}}\left(\begin{array}{ccccc}
2 & -1 & & & \\
-1 & 2 & -1 & & \\
& -1 & 2 & -1 & \\
& & \ddots & \ddots & -1 \\
& & & -1 & 2
\end{array}\right)
$$

$$
\begin{aligned}
& \mathbf{u}_{J}(t) \approx\left[u\left(t, x_{1}\right), \ldots, u\left(t, x_{J-1}\right)\right]^{T} \text { solves } \\
& \qquad \quad d \mathbf{u}_{J}=\left[-\varepsilon A^{\mathrm{D}} \mathbf{u}_{J}+\mathbf{f}\left(\mathbf{u}_{J}\right)\right] d t+\sigma d \mathbf{W}_{J}(t)
\end{aligned}
$$

$\mathbf{W}_{J}(t):=\left[W\left(t, x_{1}\right), \ldots, W\left(t, x_{J-1}\right)\right]^{T}$.

## Discretise in time :

Methods : Euler-Maruyama, Milstein etc
We examine semi-implicit Euler-Maruyama method wtih time step
$\Delta t>0$

- This has good stability properties

Get approximation $\mathbf{u}_{J, n}$ to $\mathbf{u}_{J}\left(t_{n}\right)$ at $t_{n}=n \Delta t$

$$
\mathbf{u}_{J, n+1}=\left(I+\Delta t \varepsilon A^{\mathrm{D}}\right)^{-1}\left[\mathbf{u}_{J, n}+\mathbf{f}\left(\mathbf{u}_{J, n}\right) \Delta t+\sigma \Delta \mathbf{W}_{n}\right]
$$

with $\mathbf{u}_{J, 0}=\mathbf{u}_{J}(0)$ and $\Delta \mathbf{W}_{n}:=\mathbf{W}_{J}\left(t_{n+1}\right)-\mathbf{W}_{J}\left(t_{n}\right)$.
$\mathbf{W}_{J}(t):=\left[W\left(t, x_{1}\right), \ldots, W\left(t, x_{J-1}\right)\right]^{T}$.

## Space-time white noise

The covariance $Q=I$

- Derive an approximation to the increment $W\left(t_{n+1}\right)-W\left(t_{n}\right)$.
- Truncate the expansion of $W(t)$ to $J$ terms.

Take as basis $\{\sqrt{2 / a} \sin (j \pi x / a)\}$ of $L^{2}(0, a)$

$$
W^{J}(t, x)=\sqrt{2 / a} \sum_{j=1}^{J} \sin \left(\frac{j \pi x}{a}\right) \beta_{j}(t)
$$

for iid Brownian motions $\beta_{j}(t)$.
$-\operatorname{Cov}\left(W^{J}\left(t, x_{i}\right), W^{J}\left(t, x_{k}\right)\right)=\mathbf{E}\left[W^{J}\left(t, x_{i}\right) W^{J}\left(t, x_{k}\right)\right]$

$$
=\frac{2 t}{a} \sum_{j=1}^{J} \sin \left(\frac{j \pi x_{i}}{a}\right) \sin \left(\frac{j \pi x_{k}}{a}\right) .
$$

Using $x_{i}=i h$ and $h=a / J$ with a trigonometric identity gives

$$
2 \sin \left(\frac{j \pi x_{i}}{a}\right) \sin \left(\frac{j \pi x_{k}}{a}\right)=\cos \left(\frac{j \pi(i-k)}{J}\right)-\cos \left(\frac{j \pi(i+k)}{J}\right)
$$

Now,

$$
\sum_{j=1}^{J} \cos \left(\frac{j \pi m}{J}\right)= \begin{cases}J, & m=0 \\ 0, & m \text { even and } m \neq 0 \\ -1, & m \text { odd }\end{cases}
$$

Therefore,

$$
\operatorname{Cov}\left(W^{J}\left(t, x_{i}\right), W^{J}\left(t, x_{k}\right)\right)=\frac{2 t}{a} \sum_{j=1}^{J} \sin \left(\frac{j \pi x_{i}}{a}\right) \sin \left(\frac{j \pi x_{k}}{a}\right)
$$

becomes

$$
\operatorname{Cov}\left(W^{J}\left(t, x_{i}\right), W^{J}\left(t, x_{k}\right)\right)=(t / h) \delta_{i k}
$$

for $i, k=1, \ldots, J$.
We now use $W^{J}(t)$ when $W(t)$ is space-time white noise. Spatial Approx. Reaction-Diffusion equation by

$$
d \mathbf{u}_{J}=\left[-\varepsilon A^{\mathrm{D}} \mathbf{u}_{J}+\mathbf{f}\left(\mathbf{u}_{J}\right)\right] d t+\sigma d \mathbf{W}^{J}(t)
$$

for $\mathbf{W}^{J}(t):=\left[W^{J}\left(t, x_{1}\right), \ldots, W^{J}\left(t, x_{J-1}\right)\right]^{T}$.
And have $\mathbf{W}^{J}(t) \sim N(\mathbf{0},(t / h) I)$.

## Discretise in time

$$
d \mathbf{u}_{J}=\left[-\varepsilon A^{\mathrm{D}} \mathbf{u}_{J}+\mathbf{f}\left(\mathbf{u}_{J}\right)\right] d t+\sigma d \mathbf{W}^{J}(t)
$$

$\mathbf{W}^{J}(t) \sim N(\mathbf{0},(t / h) I)$.
For a time step $\Delta t>0$, the semi-implicit Euler-Maruyama method gives

$$
\mathbf{u}_{J, n+1}=\left(I+\varepsilon A^{\mathrm{D}} \Delta t\right)^{-1}\left[\mathbf{u}_{J, n}+\Delta t \mathbf{f}\left(\mathbf{u}_{J, n}\right)+\sigma \Delta \mathbf{W}_{n}\right]
$$

and $\Delta \mathbf{W}_{n} \sim N(\mathbf{0},(\Delta t / h) I)$ iid.

```
function [t,ut]=spde_fd_d_white(u0,T,a,N,J, epsilon, sigma,fh
Dt=T/N; t=[0:Dt:T]'; h=a/J;
% set matrices
e = ones (J+1,1); A = spdiags ([le -2*e e], -1:1, J+1, J+1)
%case {'dirichlet','d'}
ind=2:J; A=A(ind,ind);
EE=speye(length(ind)) -Dt*epsilon*A/h/h;
ut=zeros(J+1,length(t)); % initialize vectors
ut(:, 1)=u0; u_n=u0(ind); % set initial condition
for k=1:N, % time loop
    fu=fhandle(u_n); Wn=sqrt(Dt/h)*randn(J-1,1);
    u_new=EE\(u_n+Dt*fu+sigma*Wn);
    ut(ind,k+1)=u_new; u_n=u_new;
end
```

Code to generate realisations of the finite difference approximation homogeneous Dirichlet boundary conditions space-time white noise.

## Galerkin approximation

Based on weak solution

$$
\langle u(t), v\rangle=\left\langle u_{0}, v\right\rangle+\int_{0}^{t}[-\langle u(s), A v\rangle+\langle f(u(s)), v\rangle] d s+\int_{0}^{t}\langle G(u(s)) d W(s), v\rangle,
$$

where

$$
\int_{0}^{t}\langle G(u(s)) d W(s), v\rangle:=\sum_{j=1}^{\infty} \int_{0}^{t}\left\langle G(u(s)) \sqrt{q_{j}} \chi_{j}, v\right\rangle d \beta_{j}(s) .
$$

- Take finite-dimensional subspace
$\tilde{V}=\operatorname{span}\left\{\psi_{1}, \psi_{2}, \ldots, \psi_{J}\right\} \subset \mathcal{D}\left(A^{1 / 2}\right)$.
Let $\tilde{P}$ be the orthogonal projection $\tilde{P}: H \rightarrow \tilde{V}$
Seek $u(t) \approx \tilde{u}(t)=\sum_{j=1}^{J} \hat{u}_{j}(t) \psi_{j}$
Initial data, we take $\tilde{u}_{0}=\tilde{P} u_{0}$
Rewrite as

$$
d \tilde{u}=[-\tilde{A} \tilde{u}+\tilde{P} f(\tilde{u})] d t+\tilde{P} G(\tilde{u}) d W(t), \quad \tilde{u}(0)=\tilde{u}_{0}
$$

where $\langle\tilde{A} w, v\rangle=\left\langle A^{1 / 2} w, A^{1 / 2} v\right\rangle$.

- Discretise in time

$$
\tilde{u}_{n+1}=(I+\Delta t \tilde{A})^{-1}\left(\tilde{u}_{n}+\tilde{P} f\left(\tilde{u}_{n}\right) \Delta t+\tilde{P} G\left(\tilde{u}_{n}\right) \Delta W_{n}\right)
$$

$$
\tilde{u}_{n+1}=(I+\Delta t \tilde{A})^{-1}\left(\tilde{u}_{n}+\tilde{P} f\left(\tilde{u}_{n}\right) \Delta t+\tilde{P} G\left(\tilde{u}_{n}\right) \Delta W_{n}\right)
$$

for $\Delta W_{n}:=\int_{t_{n}}^{t_{n+1}} d W(s)$.

- In practice, it is necessary to approximate $G$ with some
$\mathcal{G}: \mathbb{R}^{+} \times H \rightarrow L_{0}^{2}$

$$
\tilde{u}_{n+1}=(I+\Delta t \tilde{A})^{-1}\left(\tilde{u}_{n}+\tilde{P} f\left(\tilde{u}_{n}\right) \Delta t+\tilde{P} \int_{t_{n}}^{t_{n+1}} \mathcal{G}\left(s ; \tilde{u}_{n}\right) d W(s)\right),
$$

- Example: $\mathcal{G}(s ; u)=G(u)$
$\mathcal{G}(s ; u)$ acts on the infinite-dimensional $U$-valued process $W(t)$. Difficult to implement as a numerical method.

Usually consider $\mathcal{G}(s ; u)=G(u) \mathcal{P}_{J_{w}}$ for the orthogonal projection $\mathcal{P}_{J_{w}}: U \rightarrow \operatorname{span}\left\{\chi_{1}, \ldots, \chi_{J_{w}}\right\}$ given an orthonormal basis $\chi_{j}$ of $U$.
$\delta$ : spatial discretisation parameter (e.g. $\delta=h$ ).

## Assumption

For some $\zeta \in(0,2]$, let Assumption on $G$ hold and, for some constants $K_{\mathcal{G}}, \theta, L>0$, let $\mathcal{G}: \mathbb{R}^{+} \times H \rightarrow L_{0}^{2}$ satisfy

$$
\begin{equation*}
\left\|\mathcal{G}\left(s ; u_{1}\right)-\mathcal{G}\left(s ; u_{2}\right)\right\|_{L_{0}^{2}} \leq L\left\|u_{1}-u_{2}\right\|, \quad \forall s>0, u_{1}, u_{2} \in H \tag{19}
\end{equation*}
$$

and for $t_{k} \leq s<t_{k+1}$

$$
\begin{equation*}
\left\|\tilde{P}\left(G(u(s))-\mathcal{G}\left(s ; u\left(t_{k}\right)\right)\right)\right\|_{L^{2}\left(\Omega, L_{0}^{2}\right)} \leq K_{\mathcal{G}}\left(\left|s-t_{k}\right|^{\theta}+\delta^{\zeta}\right) . \tag{20}
\end{equation*}
$$

This assumption holds for $\mathcal{G}(s, u) \equiv \mathcal{G}(u):=G(u) \mathcal{P}_{J_{w}}$ for a broad class of $Q$-Wiener processes.

Under set of conditions on the Galerkin subspace $\tilde{V}$, we prove strong convergence.

## Theorem (strong convergence)

Let the following assumptions hold:

1. the Assumptions for unique mild solution.
2. the initial data $u_{0} \in L^{2}\left(\Omega, \mathcal{F}_{0}, \mathcal{D}(A)\right)$.
3. Suppose that $\tilde{A}^{-1} \in \mathcal{L}(H)$ satisfies $\tilde{A}^{-1} \tilde{A}=I$ on $\tilde{V}$ and $\tilde{A}^{-1}(I-\tilde{P})=0$ and is non-negative definite. Further, for some $C, \delta>0$

$$
\left\|\left(\tilde{A}^{-1}-A^{-1}\right) f\right\| \leq C \delta^{2}\|f\|, \quad \forall f \in H
$$

4. Assumption on $\mathcal{G}$ for some $\theta>0$ and $\zeta \in(0,2]$.

If $\Delta t / \delta^{2}$ is fixed, then for each $\epsilon>0$, there exists $K>0$ such that

$$
\max _{0 \leq t_{n} \leq T}\left\|u\left(t_{n}\right)-\tilde{u}_{n}\right\|_{L^{2}(\Omega, H)} \leq K\left(\Delta t^{(\zeta-\epsilon) / 2}+\Delta t^{\theta}\right)
$$

Proof: Assume without loss of generality that $\Delta t / \delta^{2}=1$.
Using the notation $\tilde{S}_{\Delta t}:=(I+\Delta t \tilde{A})^{-1}$,
Scheme after $n$ steps :
$\tilde{u}_{n}=\tilde{S}_{\Delta t}^{n} \tilde{P} u_{0}+\sum_{k=0}^{n-1} \tilde{S}_{\Delta t}^{n-k} \tilde{P} f\left(\tilde{u}_{k}\right) \Delta t+\sum_{k=0}^{n-1} \tilde{S}_{\Delta t}^{n-k} \tilde{P} \int_{t_{k}}^{t_{k+1}} \mathcal{G}\left(s, \tilde{u}_{k}\right) d W(s)$.
Subtracting from the mild solution (14),
$u\left(t_{n}\right)-\tilde{u}_{n}=I+I I+$ III for

$$
\begin{aligned}
\text { I }: & =\left(e^{-t_{n} A} u_{0}-\tilde{S}_{\Delta t}^{n} \tilde{P} u_{0}\right), \\
\text { II } & :=\sum_{k=0}^{n-1}\left(\int_{t_{k}}^{t_{k+1}} e^{-\left(t_{n}-s\right) A} P f(u(s)) d s-\tilde{S}_{\Delta t}^{n-k} \tilde{P} f\left(\tilde{u}_{k}\right) \Delta t\right), \\
\text { III } & :=\sum_{k=0}^{n-1} \int_{t_{k}}^{t_{k+1}}\left(e^{-\left(t_{n}-s\right) A} G(u(s))-\tilde{S}_{\Delta t}^{n-k} \tilde{P} \mathcal{G}\left(s, \tilde{u}_{k}\right)\right) d W(s) .
\end{aligned}
$$

To treat I and II : like deterministic case.

$$
\|\mathrm{I}+\mathrm{II}\|_{L^{2}(\Omega, H)} \leq C_{\mathrm{I}+\mathrm{II}}\left(\Delta t+\delta^{2}\right) \Delta t^{-\epsilon}
$$

for a constant $C_{I+I I}$.

We break III into four further parts by writing

$$
e^{-\left(t_{n}-s\right) A} G(u(s))-\tilde{S}_{\Delta t}^{n-k} \tilde{P} \mathcal{G}\left(s, \tilde{u}_{k}\right)=X_{1}+X_{2}+X_{3}+X_{4}
$$

for

$$
\begin{array}{ll}
X_{1}:=\left(e^{-\left(t_{n}-s\right) A}-e^{-\left(t_{n}-t_{k}\right) A}\right) G(u(s)), & X_{2}:=\left(e^{-\left(t_{n}-t_{k}\right) A}-\tilde{S}_{\Delta t}^{n-k} \tilde{P}\right) G(u(s)), \\
X_{3}:=\tilde{S}_{\Delta t}^{n-k} \tilde{P}\left(G(u(s))-\mathcal{G}\left(s ; u\left(t_{k}\right)\right)\right), & X_{4}:=\tilde{S}_{\Delta t}^{n-k} \tilde{P}\left(\mathcal{G}\left(s ; u\left(t_{k}\right)\right)-\mathcal{G}\left(s ; \tilde{u}_{k}\right)\right) .
\end{array}
$$

- To estimate III in $L^{2}(\Omega, H)$, we estimate $\operatorname{III}_{i}=\int_{0}^{t_{n}} X_{i} d W(s)$ separately using the triangle inequality.
Use Itô's isometry and estimates from semigroup theory and Gronwall.

Example (reaction-diffusion equation on $(0,1)$ )

$$
d u=[-A u+f(u)] d t+G(u) d W(t)
$$

where $A=-\Delta$ with $\mathcal{D}(A)=H^{2}(0,1) \cap H_{0}^{1}(0,1)$

- $W(t)$ a $Q$-Wiener process.

If $G(u) W(t)$ is smooth $\zeta=1$,
Choose $\mathcal{G}(u)=G(u) \mathcal{P}_{j_{w}}$ with $J_{w}$ sufficiently large .
For initial data $u_{0} \in H^{2}(0,1) \cap H_{0}^{1}(0,1)$, have

$$
\max _{0 \leq t_{n} \leq T}\left\|u\left(t_{n}\right)-\tilde{u}_{n}\right\|_{L^{2}(\Omega, H)}=\mathcal{O}\left(\Delta t^{1 / 2}+\delta\right) .
$$

- Additive noise : improved rate convergence

$$
\max _{0 \leq t_{n} \leq T}\left\|u\left(t_{n}\right)-\tilde{u}_{n}\right\|_{L^{2}(\Omega, H)}=\mathcal{O}\left(\Delta t^{1-\epsilon}+\delta\right)
$$

- For additive space-time white noise, $W(t)$ cylindrical Wiener process, $\zeta \in(0,1 / 2)$ and

$$
\max _{0 \leq t_{n} \leq T}\left\|u\left(t_{n}\right)-\tilde{u}_{n}\right\|_{L^{2}(\Omega, H)}=\mathcal{O}\left(\Delta t^{(1-\epsilon) / 4}+\Delta t^{\theta}\right), \quad \epsilon>0 .
$$

## Spectral Galerkin

$$
d u=[-A u+f(u)] d t+G(u) d W(t)
$$

periodic boundary conditions on the domains $D=(0, a)$
Approximate using the Galerkin subspace
$\tilde{V}=V_{J}:=\operatorname{span}\left\{\phi_{1}, \ldots, \phi_{J}\right\}$
$\phi_{j}$ eigenfunctions of $A$.

$$
P_{\jmath u}:=\sum_{j=1}^{J} \hat{u}_{j} \phi_{j}, \quad \hat{u}_{j}:=\frac{1}{\left\|\phi_{j}\right\|^{2}}\left\langle u, \phi_{j}\right\rangle, \quad u \in H .
$$

- Spatial discretisation. $P_{J}=P_{J_{w}}$.

$$
d u_{\jmath}=\left[-A_{\jmath} u_{\jmath}+P_{\jmath} f\left(u_{\jmath}\right)\right] d t+P_{\jmath} G\left(u_{\jmath}\right) d W(t), \quad u_{\jmath}(0)=P_{\jmath} u_{0}
$$

- Time discretisation

$$
u_{J, n+1}=\left(I+\Delta t A_{J}\right)^{-1}\left(u_{J, n}+\Delta t P_{J} f\left(u_{J, n}\right)+P_{\jmath} G(u) \mathcal{P}_{J_{w}} \Delta W_{n}\right) .
$$

Allen Cahn : $d u=\left(u_{x x}+u-u^{3}\right) d t+d W$.


```
function [t,u,ut]=spde_AC(u0,T,a,N,Jref,r,sigma)
Dt=T/N; t=[0:Dt:T]';
% set Lin Operators
kk = 2*pi*[0:Jref/2 -Jref/2+1:-1]'/a;
Dx = (1i*kk); MM=-Dx.^ 2;
EE=1./(1+Dt*MM);
% get form of noise
iFspace=1; bj = get_oned_bj(Dt,Jref,a,r);
% set initial condition
ut(:,1)=u0; u=u0(1:Jref); uh0=fft(u); uh=uh0;
u=real(ifft(uh));
for n=1:N % time loop
    fhu=fft(u-u. - 3);
    dW=get_oned_dW(bj,1,iFspace,1);
    gu=sigma; % function for noise term
    gdWh=fft(gu.*real(ifft(dW))); %
    uh_new=EE.*(uh+Dt*fhu+gdWh);
    uh=uh_new;
    u=real(ifft(uh));
    ut(1:Jref,n+1)=u(:, 1);
end
ut(Jref+1,:)=ut(1,:); u=[u; u(1,:)]; % periodic
```


## Convergence

Allen Cahn : $d u=\left(u_{x x}+u-u^{3}\right) d t+d W$.

- Additive noise: improved rate convergence

$$
\max _{0 \leq t_{n} \leq T}\left\|u\left(t_{n}\right)-\tilde{u}_{n}\right\|_{L^{2}(\Omega, H)}=\mathcal{O}\left(\Delta t^{1-\epsilon}+\delta\right) .
$$

- For additive space-time white noise, $W(t)$ cylindrical Wiener process, $\zeta \in(0,1 / 2)$ and

$$
\max _{0 \leq t_{n} \leq T}\left\|u\left(t_{n}\right)-\tilde{u}_{n}\right\|_{L^{2}(\Omega, H)}=\mathcal{O}\left(\Delta t^{(1-\epsilon) / 4}+\Delta t^{\theta}\right), \quad \epsilon>0 .
$$



## Galerkin Finite Element

$$
d u=[\varepsilon \Delta u+f(u)] d t+g(u) d W(t), \quad u(0)=u_{0} \in L^{2}(D)
$$

Let $\tilde{V}=V^{h}=$ space of continuous and piecewise linear functions.
Take uniform mesh of $n_{e}$ elements with vertices
$0=x_{0}<\cdots<x_{n_{e}}=a$. mesh width $h=a / n_{e}$.
Finite element approximation $u_{h}(t) \in V^{h}$

$$
u_{h}(t, x)=\sum_{j=1}^{J} u_{j}(t) \phi_{j}(x)
$$

- Space discretisation

$$
d u_{h}=\left[-\varepsilon A_{h} u_{h}+P_{h, L^{2}} f\left(u_{h}\right)\right] d t+P_{h, L^{2}} G\left(u_{h}\right) d W(t)
$$

where $A_{h}$ is defined by $\left\langle A_{h} w, v\right\rangle=a(w, v)$.

- Time discretisation

$$
u_{h, n+1}=\left(I+\Delta t \varepsilon A_{h}\right)^{-1}\left(u_{h, n}+P_{h, L^{2}} f\left(u_{h, n}\right) \Delta t+P_{h, L^{2}} \mathcal{G}\left(u_{h, n}\right) \Delta W_{n}\right)
$$

## Equ. for coefficients

$$
u_{h}(t, x)=\sum_{j=1}^{J} u_{j}(t) \phi_{j}(x)
$$

Note that $\mathcal{P}_{J_{w}}: U \rightarrow \operatorname{span}\left\{\chi_{1}, \ldots, \chi_{J_{w}}\right\}$ and $P_{J}: H \rightarrow V^{h}$.
Distinct operators.

- Let $\mathbf{u}_{h}(t):=\left[u_{1}(t), u_{2}(t), \ldots, u_{J}(t)\right]^{T}$. Then, we get

$$
M d \mathbf{u}_{h}=\left[-\varepsilon K \mathbf{u}_{h}+\mathbf{f}\left(\mathbf{u}_{h}\right)\right] d t+\mathbf{G}\left(\mathbf{u}_{h}\right) d W(t)
$$

$\mathbf{f}\left(\mathbf{u}_{h}\right) \in \mathbb{R}^{J}$ has elements $f_{j}=\left\langle f\left(u_{h}\right), \phi_{j}\right\rangle_{L^{2}(0, a)}$.
$M$ is the mass matrix with elements $m_{i j}=\left\langle\phi_{i}, \phi_{j}\right\rangle_{L^{2}(0, a)}$
$K$ is the diffusion matrix with elements $k_{i j}=a\left(\phi_{i}, \phi_{j}\right)$.
Finally, $\mathbf{G}: \mathbb{R}^{J} \rightarrow \mathcal{L}\left(U, \mathbb{R}^{J}\right)$
and $\mathbf{G}\left(\mathbf{u}_{h}\right) \chi$ has $j$ th coefficient

$$
\left\langle G\left(u_{h}\right) \chi, \phi_{j}\right\rangle_{L^{2}(0, a)}
$$

for $\chi \in U$.

## Time discrete

$$
M d \mathbf{u}_{h}=\left[-\varepsilon K \mathbf{u}_{h}+\mathbf{f}\left(\mathbf{u}_{h}\right)\right] d t+\mathbf{G}\left(\mathbf{u}_{h}\right) d W(t)
$$

- Use semi-implicit Euler-Maruyama

$$
(M+\Delta t \varepsilon K) \mathbf{u}_{h, n+1}=M \mathbf{u}_{h, n}+\Delta t \mathbf{f}\left(\mathbf{u}_{h, n}\right)+G_{h}\left(\mathbf{u}_{h, n}\right) \Delta \mathbf{W}_{n}
$$

- The term $G_{h}\left(\mathbf{u}_{h, n}\right) \in \mathbb{R}^{J \times J_{w}}$ has $j, k$ entry $\left\langle G\left(\mathbf{u}_{h, n}\right) \chi_{k}, \phi_{j}\right\rangle_{L^{2}(0, a)}$
- Term $\Delta \mathbf{W}_{n}$ is a vector in $\mathbb{R}^{J_{w}}$ with entries $\left\langle W\left(t_{n+1}\right)-W\left(t_{n}\right), \chi_{k}\right\rangle_{L^{2}(0, a)}$ for $k=1, \ldots, J_{w}$.
- Practical computations:

Write the $Q$-Wiener process $W(t)$ as series.
Then $G_{h}\left(\mathbf{u}_{h, n}\right) \Delta \mathbf{W}_{n}$ is found by multiplying the matrix $G_{h}$ by the vector of coefficients

$$
\left[\sqrt{q_{1}}\left(\beta_{1}\left(t_{n+1}\right)-\beta_{1}\left(t_{n}\right)\right), \ldots, \sqrt{q J_{w}}\left(\beta_{J_{w}}\left(t_{n+1}\right)-\beta_{J_{w}}\left(t_{n}\right)\right)\right]^{T} .
$$

Stochastic Navier Stokes:

(b)

(a) $Q$-Wiener process $W(t)$ in $H_{0}^{1}(0,1)$
(b) space-time white noise $\left(H_{0}^{1 / 2}(0,1)\right)$.

## Numerical Convergence

We approximate

$$
\begin{equation*}
\left\|u(T)-u_{h, N}\right\|_{L^{2}\left(\Omega, L^{2}(0, a)\right)} \approx\left(\frac{1}{M} \sum_{m=1}^{M}\left\|u_{\mathrm{ref}}^{m}-u_{h, N}^{m}\right\|_{L^{2}(0, a)}^{2}\right)^{1 / 2} \tag{21}
\end{equation*}
$$

Finite element and semi-implicit Euler approximation of the stochastic Nagumo equation.


$\log \log$ plot of the approximation of $\left\|u(1)-u_{h, N}\right\|_{L^{2}\left(\Omega, L^{2}(0, a)\right)}$
(a) the spatial mesh size $h$ is varied and
(b) as the time step $\Delta t$ is varied.

Multiplicative noise gives errors of order $\Delta t^{1 / 2}$
Additive noise gives errors of order $\Delta t$.

## Exponential integrator for additive noise

The semi-implicit Euler-Maruyama method uses a basic increment $\Delta W_{n}$ to approximate $W(t)$.
An alternative time stepping method: use the mild solution/ variation of constants formula for SPDEs.

$$
u(t)=e^{t A} u(0)+\int_{0}^{t} e^{(t-s) A} f(u(s)) d s+\int_{0}^{t} e^{(t-s) A} g(u(s)) d W(s)
$$

Consider discretization in space via : $u_{J}(t)=\sum_{j=1}^{J} \hat{u}_{j}(t) \phi_{j}$. The variation of constants formula in each mode with $t_{n}=n \Delta t$

$$
\begin{aligned}
\hat{u}_{j}\left(t_{n+1}\right)= & e^{-\Delta t \lambda_{j}} \hat{u}_{j}\left(t_{n}\right)+\int_{t_{n}}^{t_{n+1}} e^{-\left(t_{n+1}-s\right) \lambda_{j}} \hat{f}_{j}(u J(s)) d s \\
& +\sigma \int_{t_{n}}^{t_{n+1}} e^{-\left(t_{n+1}-s\right) \lambda_{j}} \sqrt{q_{j}} d \beta_{j}(s)
\end{aligned}
$$

To obtain a numerical method, we approximate $\hat{f}_{j}\left(u_{J}(s)\right)$ by $\hat{f}_{j}\left(u_{J}\left(t_{n}\right)\right)$ for $s \in\left[t_{n}, t_{n+1}\right)$ and evaluate the integral, to find

$$
\int_{t_{n}}^{t_{n+1}} e^{-\left(t_{n+1}-s\right) \lambda_{j}} \hat{f}_{j}\left(u_{J}(s)\right) d s \approx \frac{1-e^{-\Delta t \lambda_{j}}}{\lambda_{j}} \hat{f}_{j}\left(u_{J}\left(t_{n}\right)\right)
$$

For the stochastic integral, we usually approximate $e^{-\left(t_{n+1}-s\right) \lambda_{j}} \approx e^{-t_{n+1} \lambda_{j}}$ and use a standard Brownian increment. However,

$$
\mathbf{E}\left[\left|\int_{0}^{t} e^{-s \lambda} d \beta_{j}(s)\right|^{2}\right]=\frac{1-e^{-2 t \lambda}}{2 \lambda}
$$

The stochastic integral $\int_{0}^{t} e^{-s \lambda} d \beta_{j}(s)$ has distribution $N\left(0,\left(1-e^{-2 t \lambda}\right) / 2 \lambda\right)$.
Hence can generate approximations $\hat{u}_{j, n}$ to $\hat{u}_{j}\left(t_{n}\right)$ using

$$
\begin{equation*}
\hat{u}_{j, n+1}=e^{-\Delta t \lambda_{j}} \hat{u}_{n, j}+\frac{1-e^{-\Delta t \lambda_{j}}}{\lambda_{j}} \hat{f}_{j}\left(u_{J, n}\right)+\sigma b_{j} R_{j, n} \tag{22}
\end{equation*}
$$

where $b_{j}:=\sqrt{q_{j}\left(1-e^{-2 \Delta t \lambda_{j}}\right) / 2 \lambda_{j}}$ and $R_{j, n} \sim N(0,1)$ iid.

- Advantage : samples the stochastic integral term exactly.

